

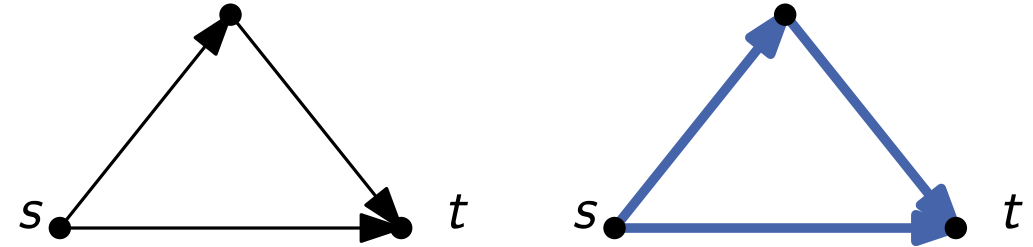
Dynamic Flows with Time-Dependent Capacities

Thomas Bläsius, **Adrian Feilhauer**, Jannik Westenfelder



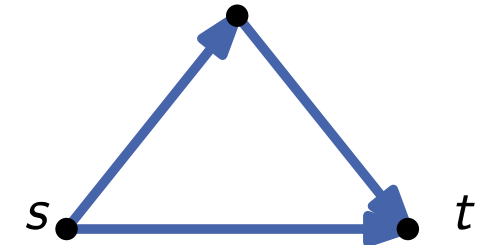
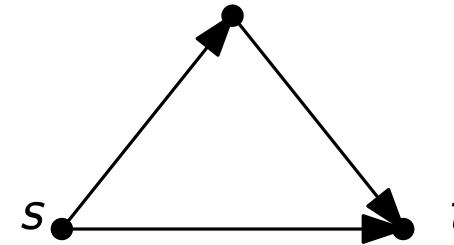
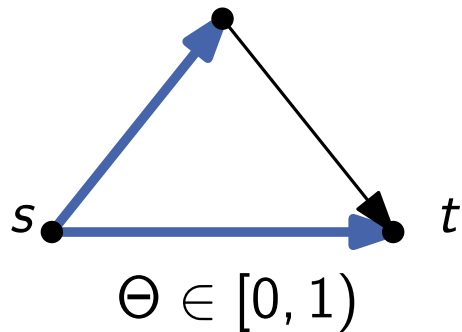
Dynamic Flows

- Network flow from source s to target t



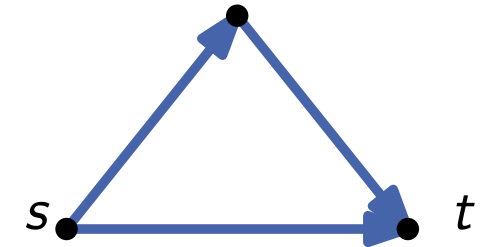
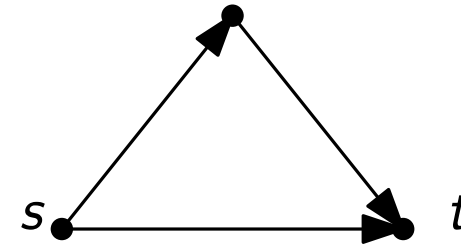
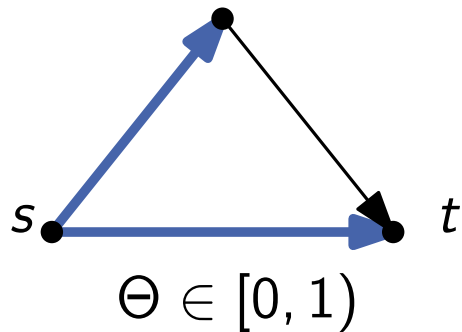
Dynamic Flows

- Network flow from source s to target t
- Traversing edges takes time



Dynamic Flows

- Network flow from source s to target t
- Traversing edges takes time
- Maximize flow reaching t before time horizon T

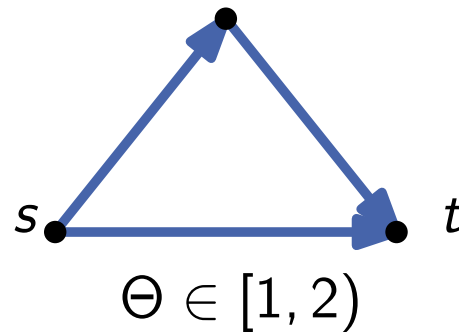
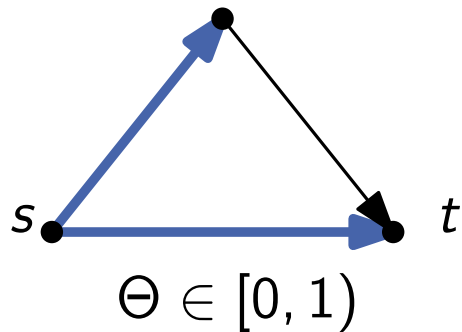
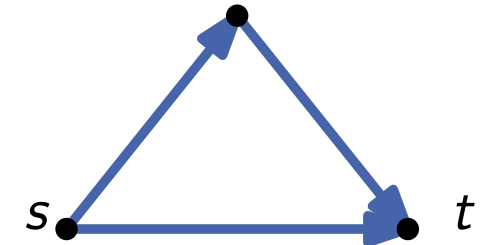
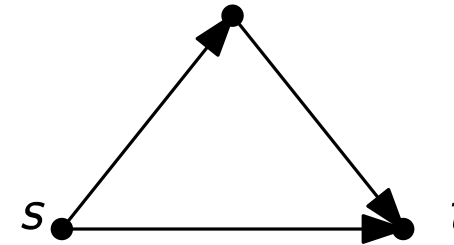


$$T = 4$$



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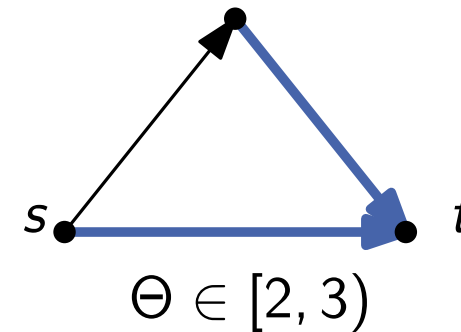
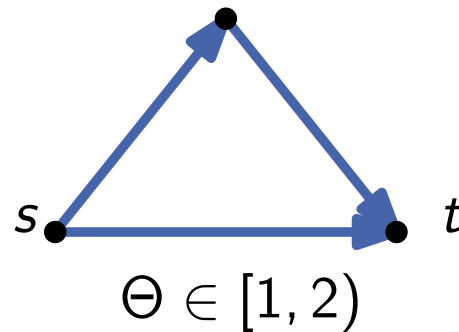
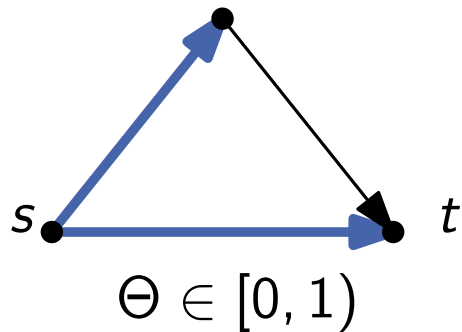
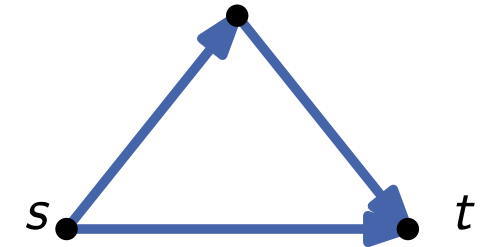
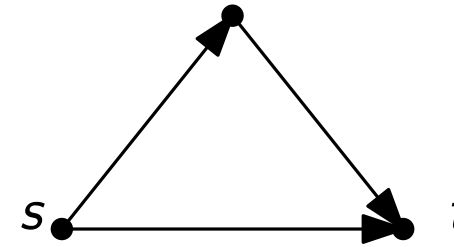


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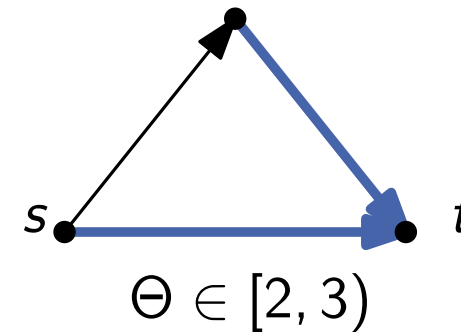
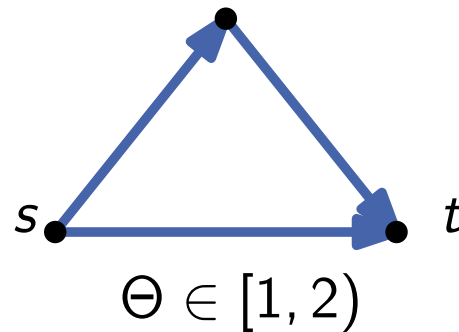
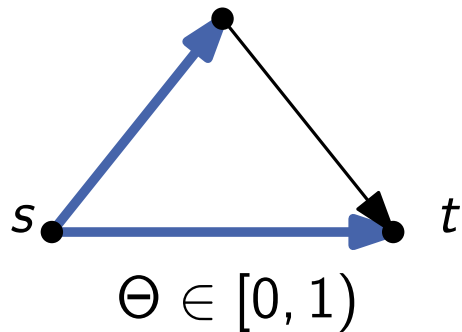
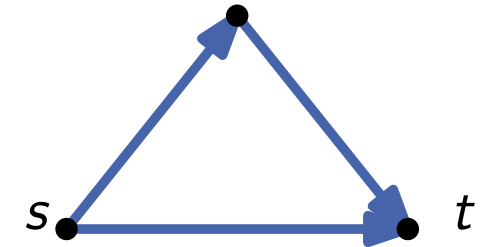
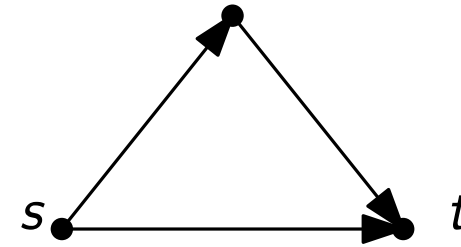


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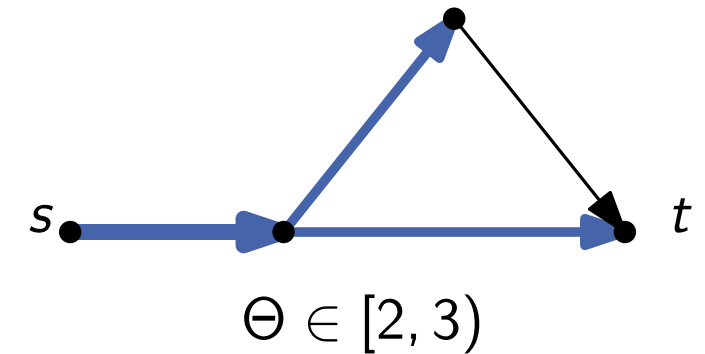
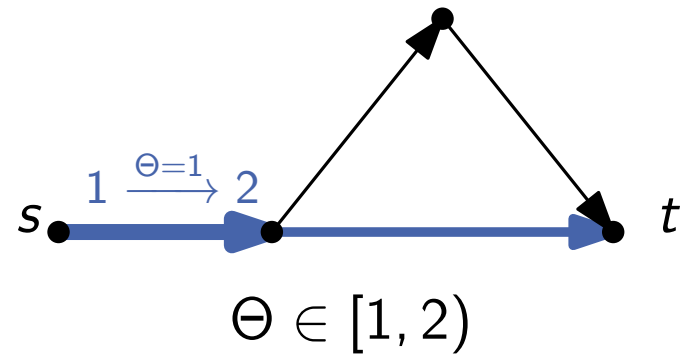
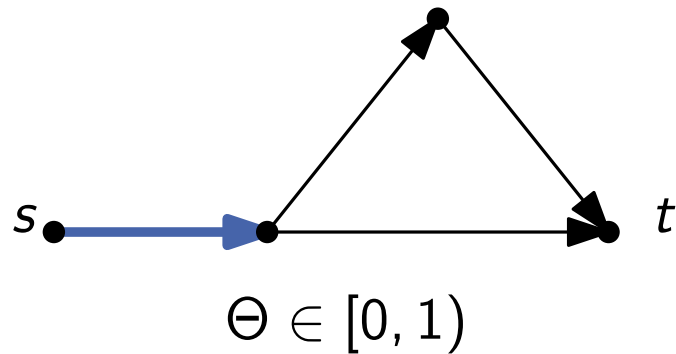
$T = 4$

- Solvable via temporally repeated flows [Ford, Fulkerson 1958]



Time Dependent Capacities

- Capacities change over time (here piecewise constant)



- Solvable via time expanded networks



Computational Complexity

Theorem:

Finding maximum dynamic flows with time dependent capacities is weakly NP-hard.

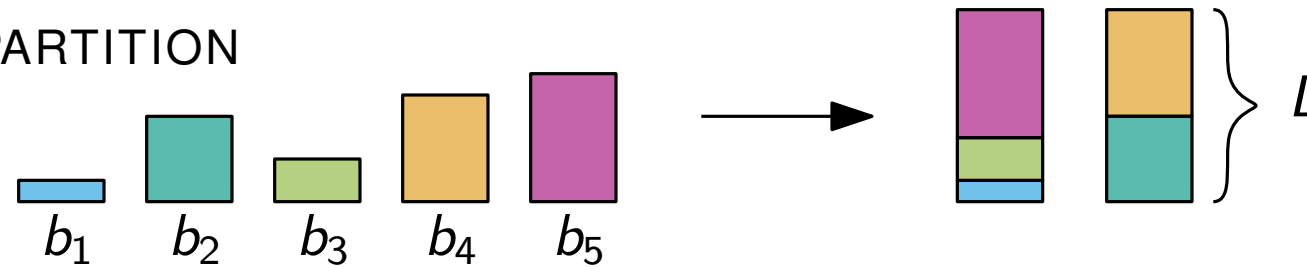
- Reduction from PARTITION

Computational Complexity

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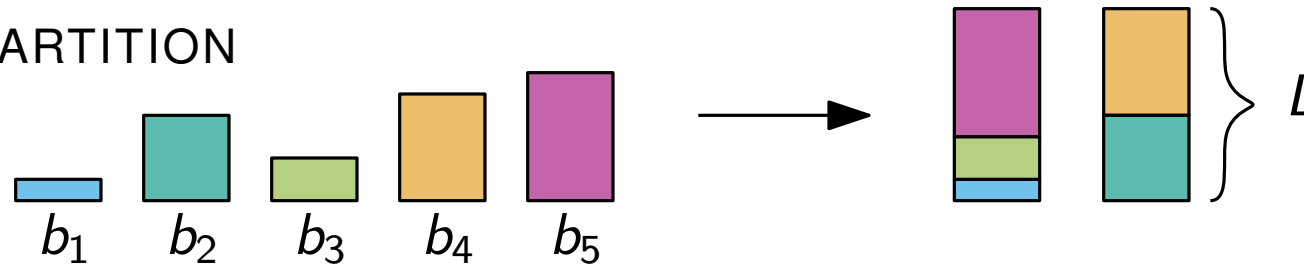


Computational Complexity

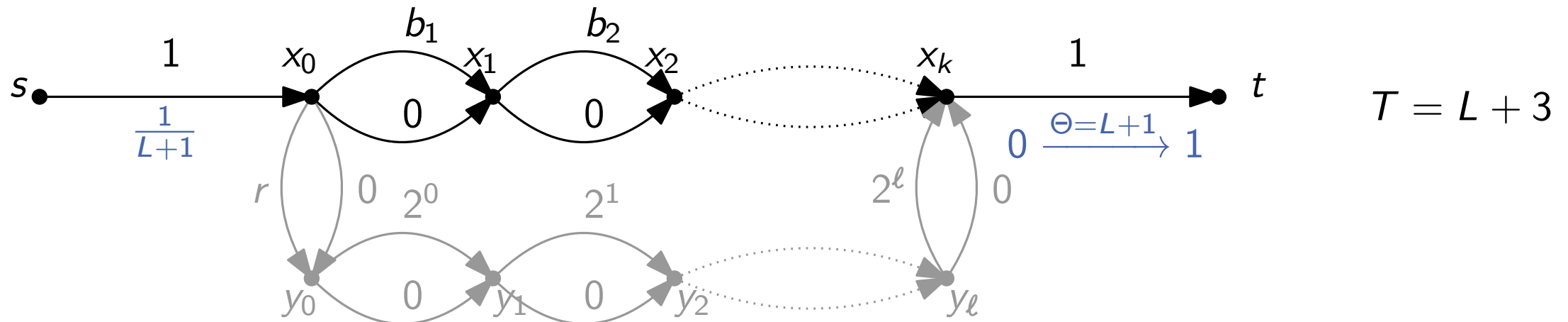
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Reduction from PARTITION



Flow of value 1 is equivalent to the PARTITION instance being solvable

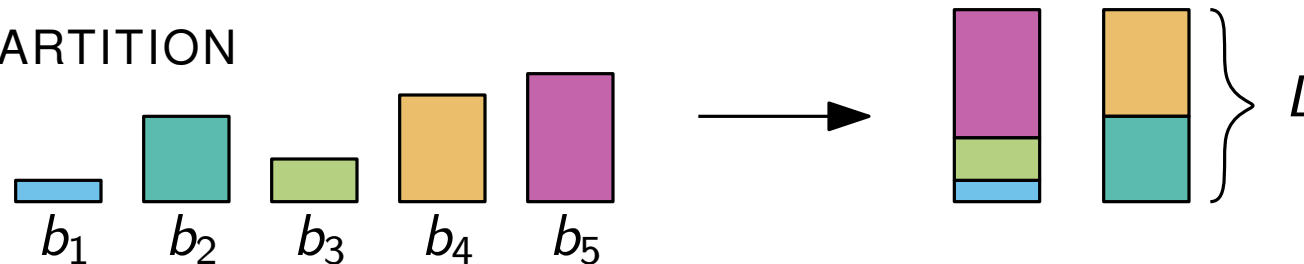


Computational Complexity

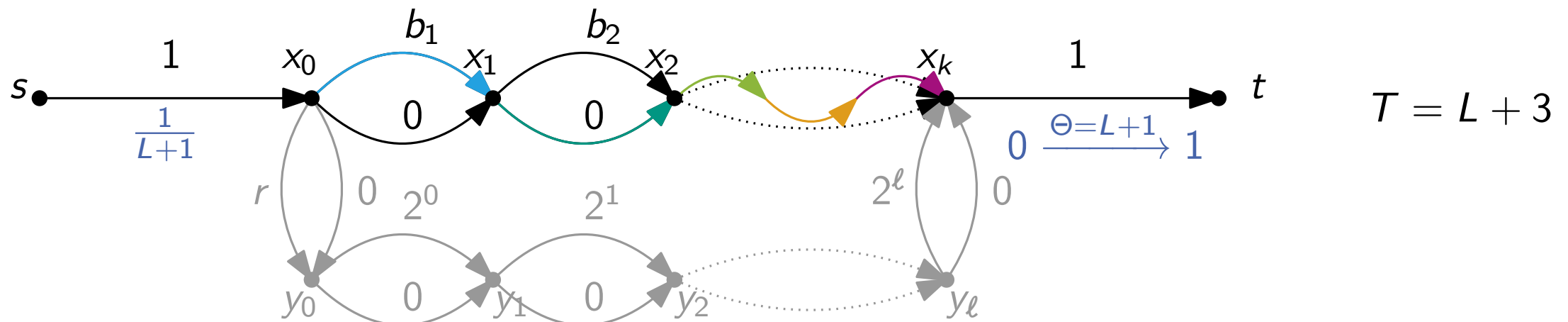
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Computational Complexity

- Pseudopolynomial solution via time expanded networks

	time-dependent capacities	time-dependent transit times
finite time horizon	hard for 1 change	
infinite considered time		



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- Potentially unwanted effects near $T \rightarrow$ infinite considered time

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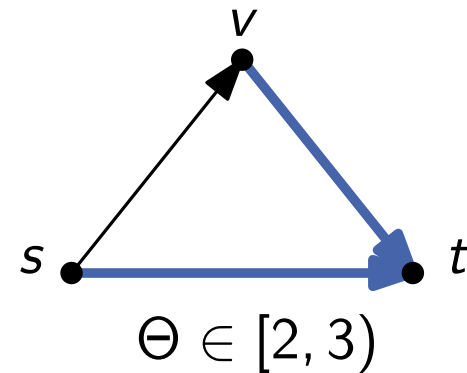
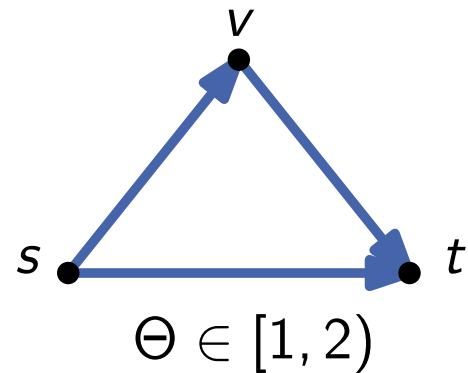
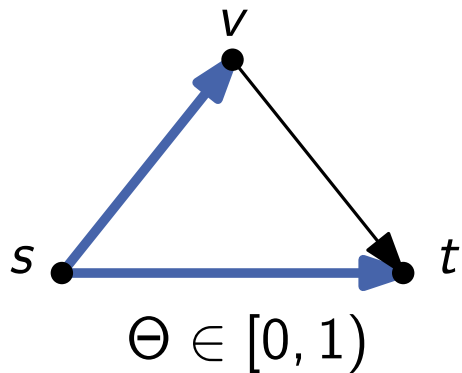
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- Is finding maximum dynamic flows in NP?
- How complicated can those maximum flows become?



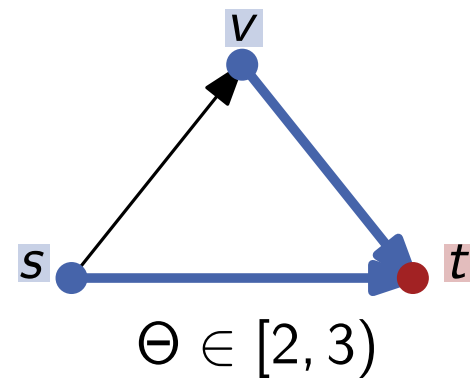
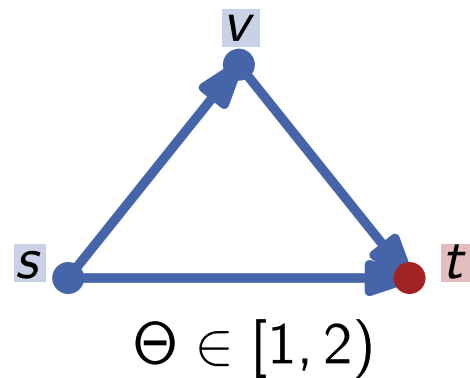
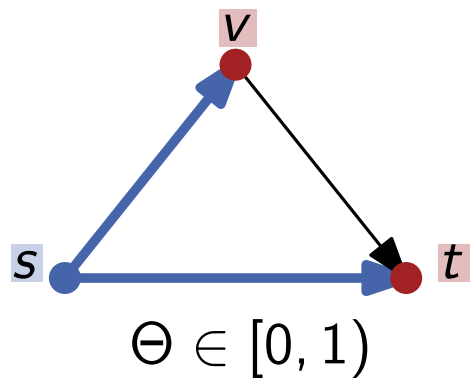
Dynamic Cut-Flow Duality

- Cuts are vertex partitions S, \bar{S}
- Cut capacity is possible flow from S to \bar{S}
- Dynamic Cuts can change over time
- Number of partition changes is the cut's *complexity*



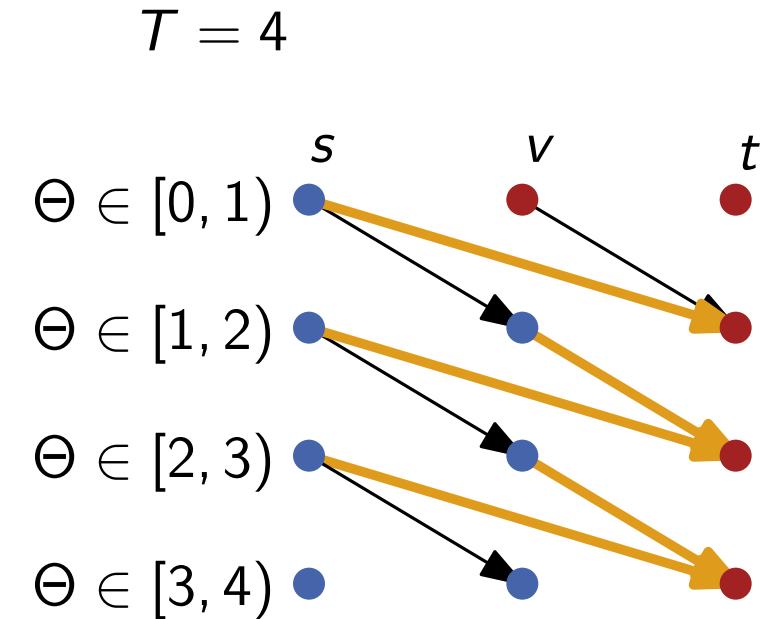
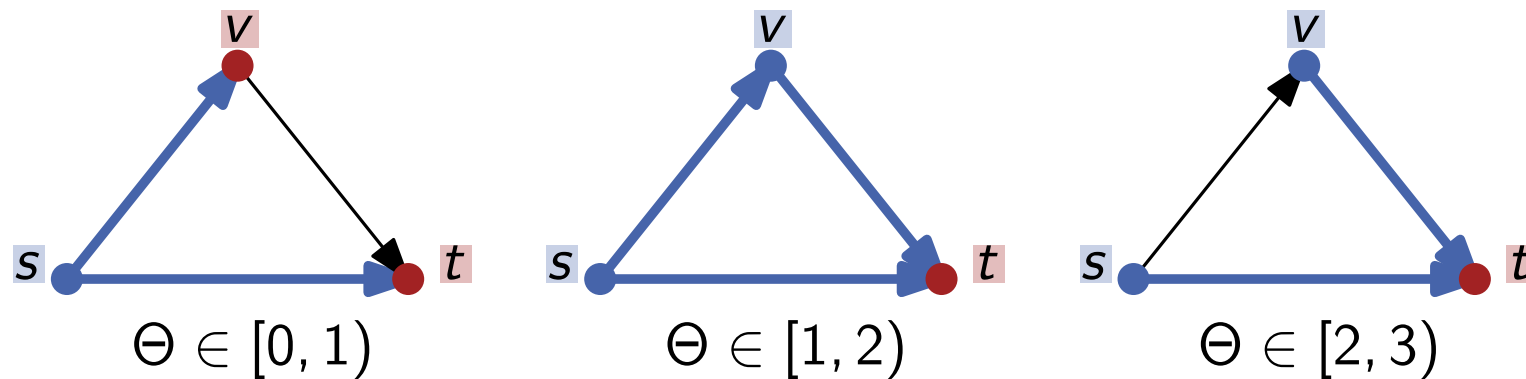
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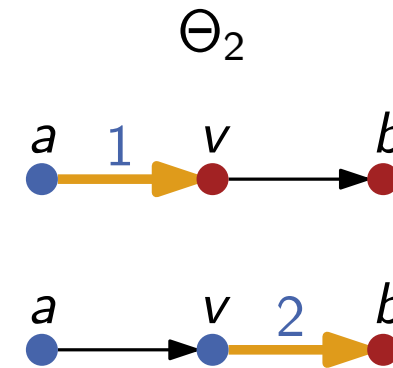
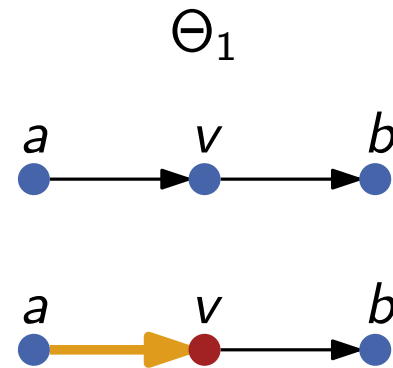
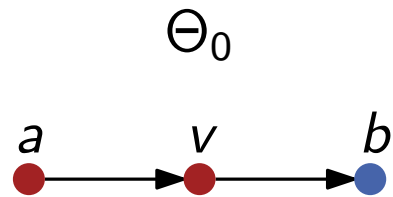


Theorem (Cut-Flow Duality [Philpott 1990]):

The capacity of a minimum dynamic cut equals the value of a maximum dynamic flow.

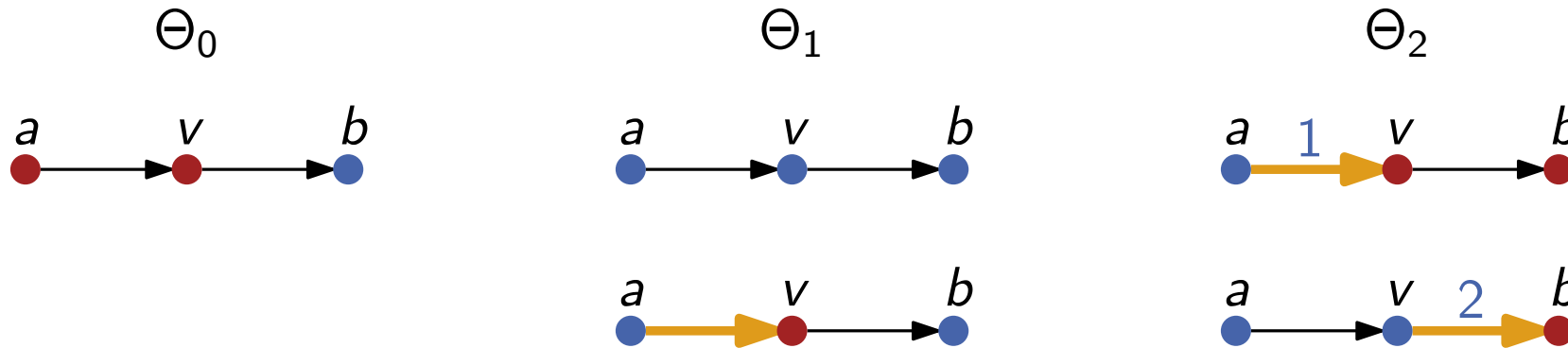
Mimicking Cuts

- How complex are minimum dynamic cuts?
- Partition changes can cascade (vertex v)



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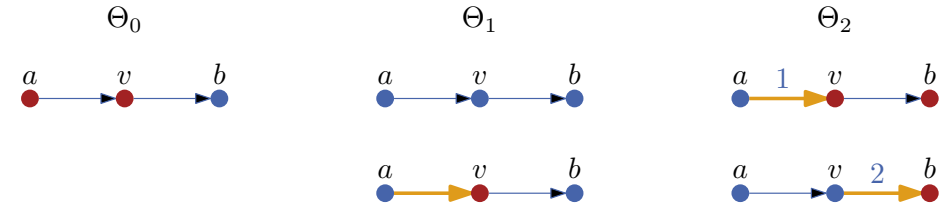


- **Idea:** use this to make vertex y mimic the behavior of x

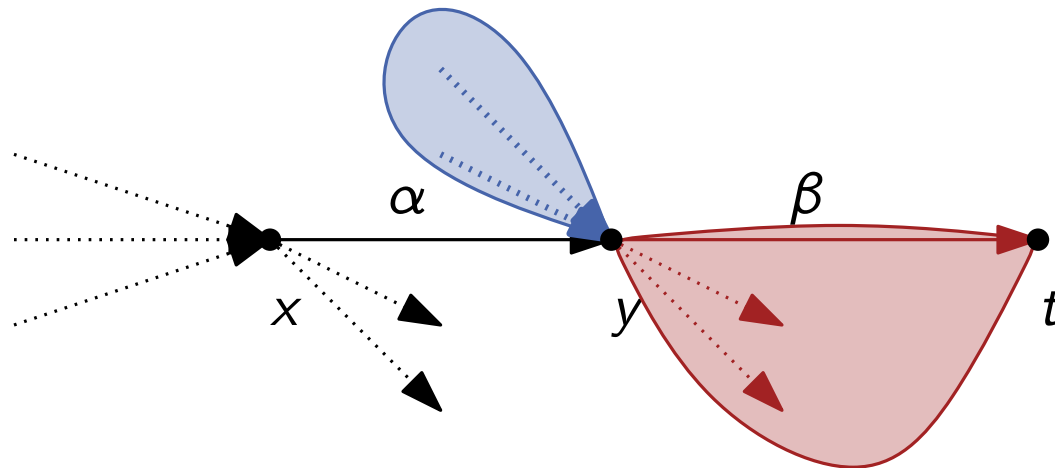


Mimicking Cuts

- How complex are minimum dynamic cuts?
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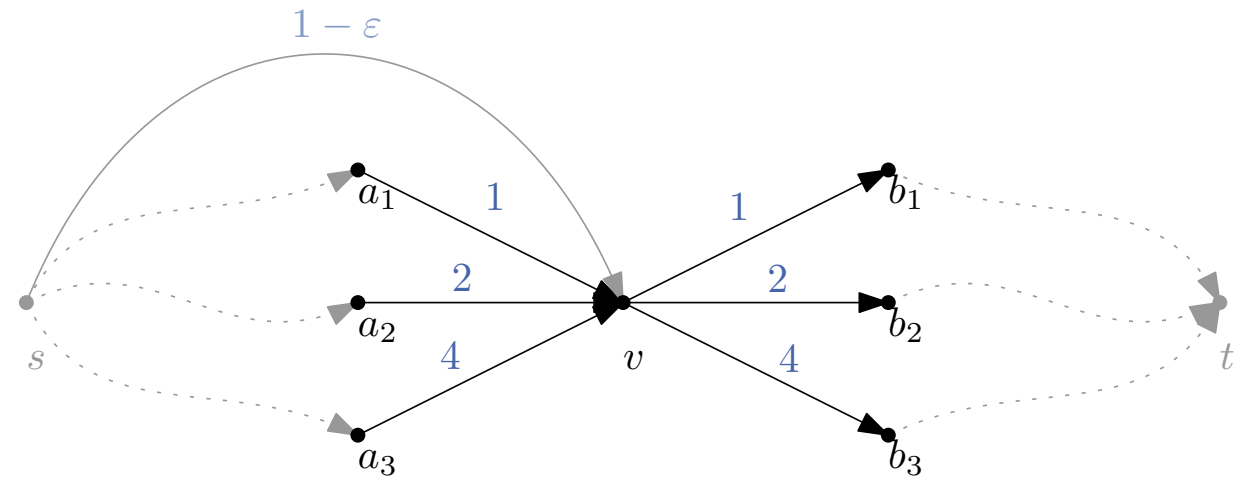
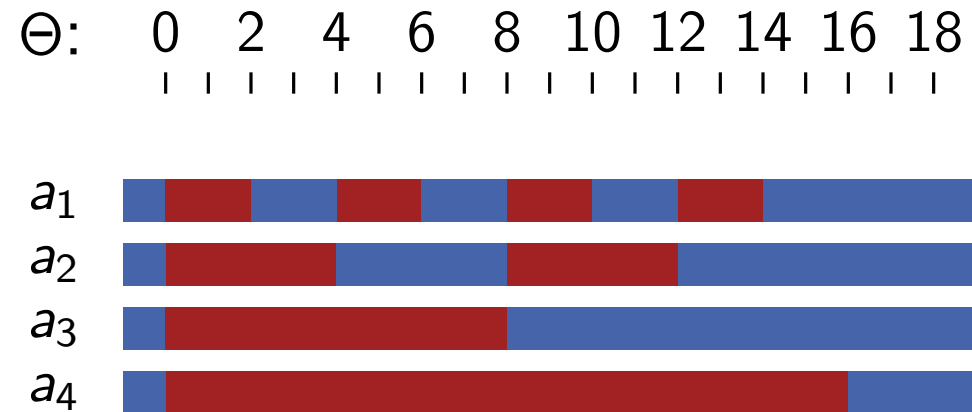


$$\alpha > \sum_{w:(y,w) \in E} U(y,w)$$

$$\beta > \sum_{w:(w,y) \in E \setminus (x,y)} U(w,y)$$

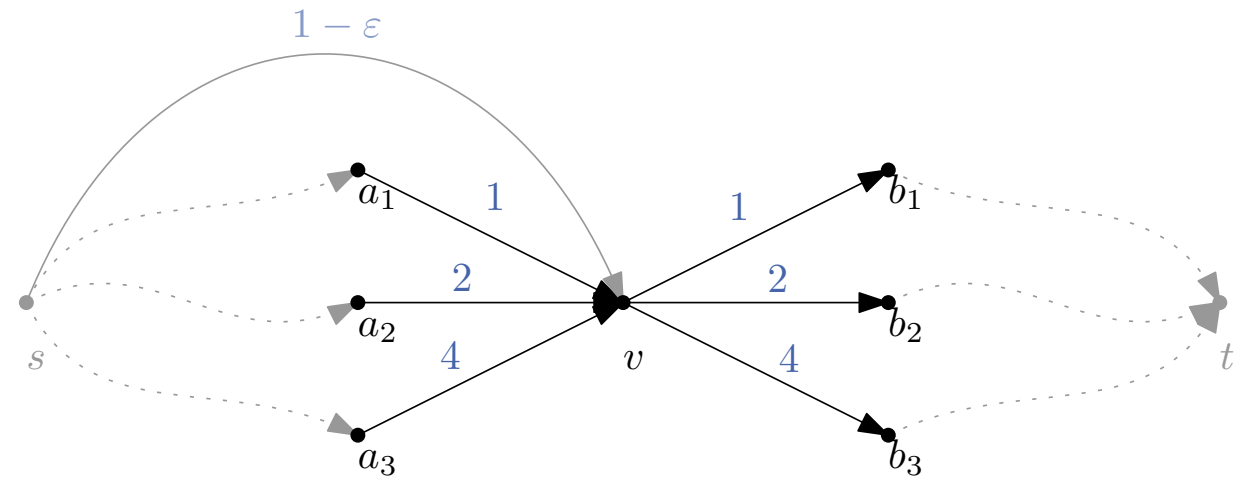
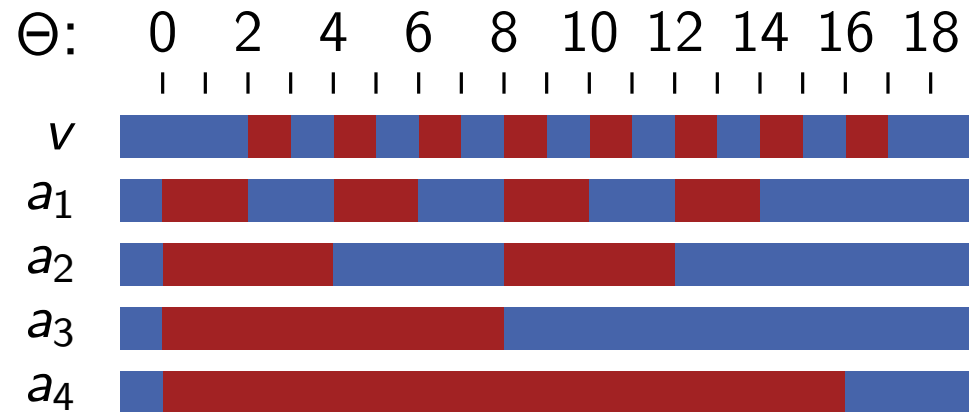
Exponentially Complex Cuts

- Given partition changes of vertices a_i



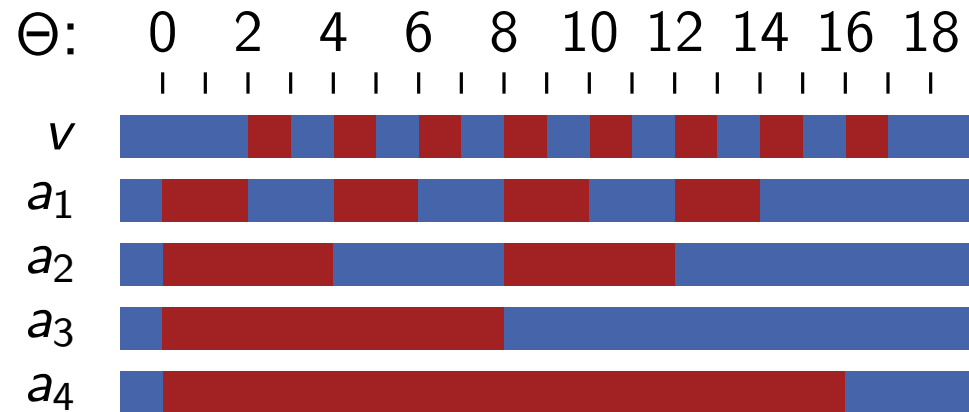
Exponentially Complex Cuts

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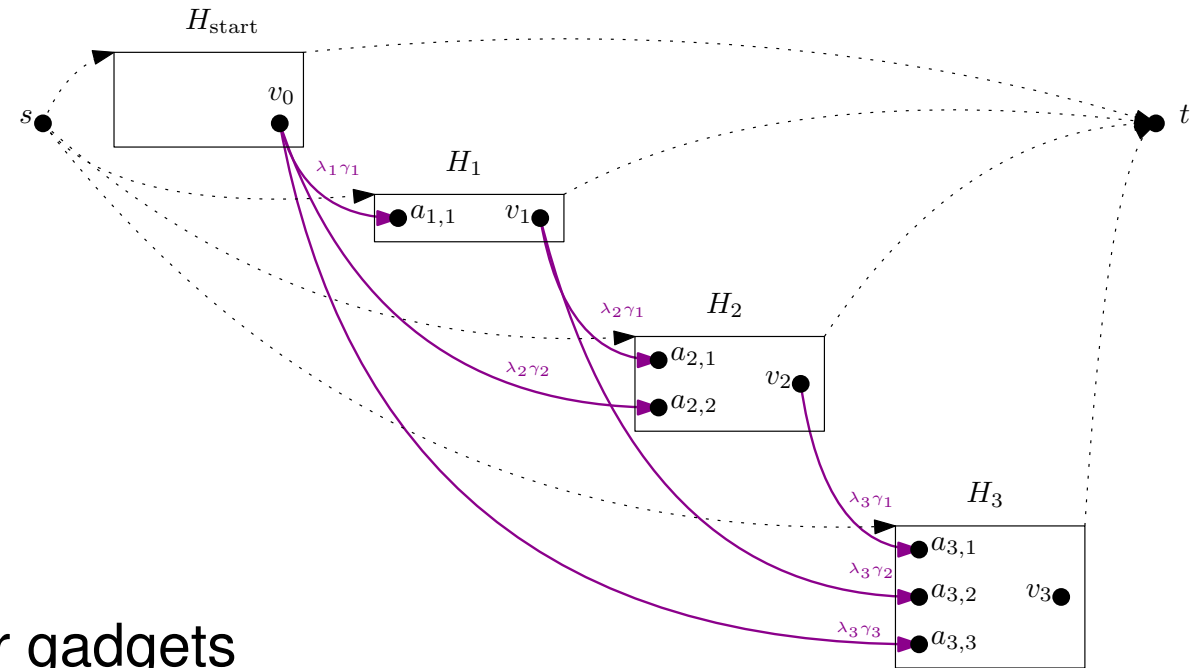


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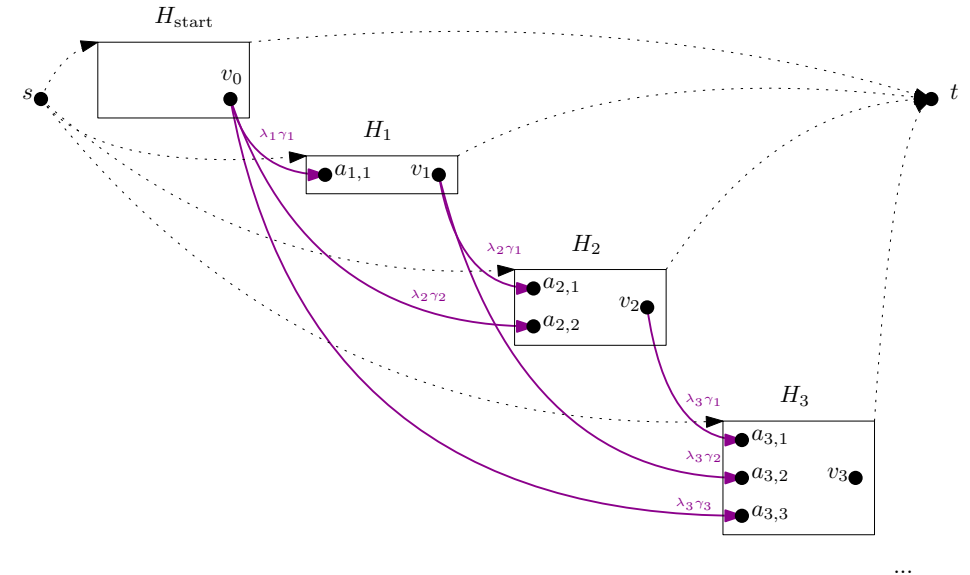
- Use smaller counters to provide a_i for larger gadgets



Theorem:
 Minimum dynamic cuts may be exponentially complex.

Exponentially Complex Flows

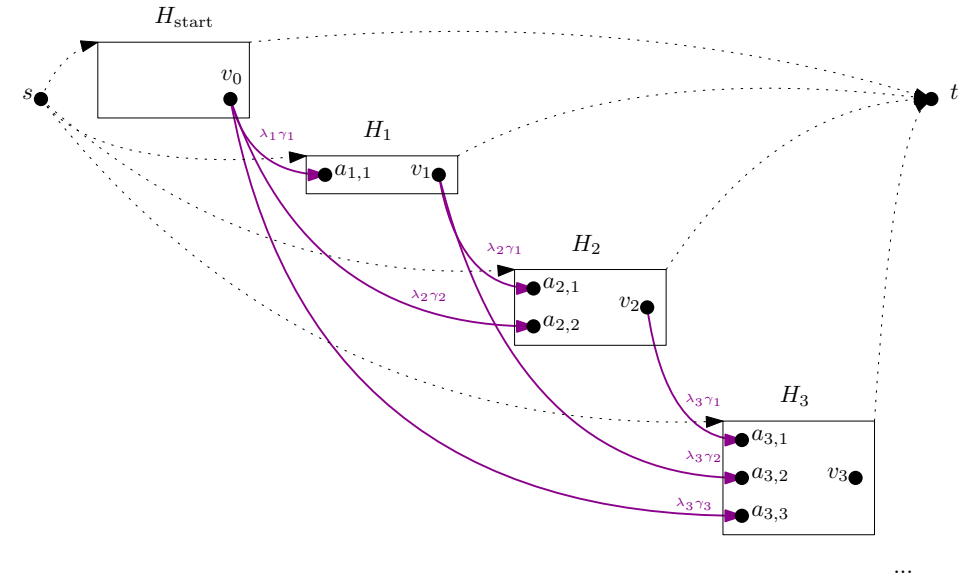
- Cut and flow complexity can occur independently
 - Simple flow and complex cut
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Exponentially Complex Flows

- Cut and flow complexity can occur independently
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- Cut-Flow-Duality is still helpful:
- Previous construction has complex cut and flow



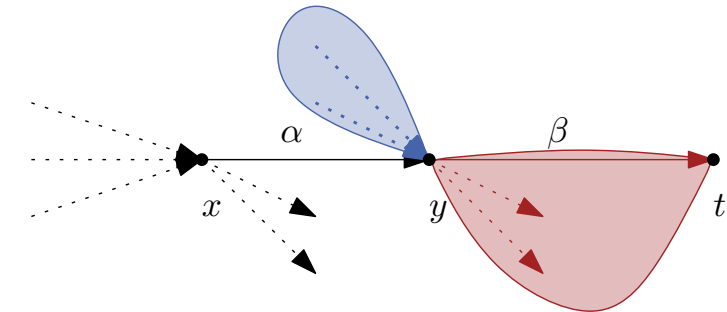
Theorem:

Maximum dynamic flows may be exponentially complex



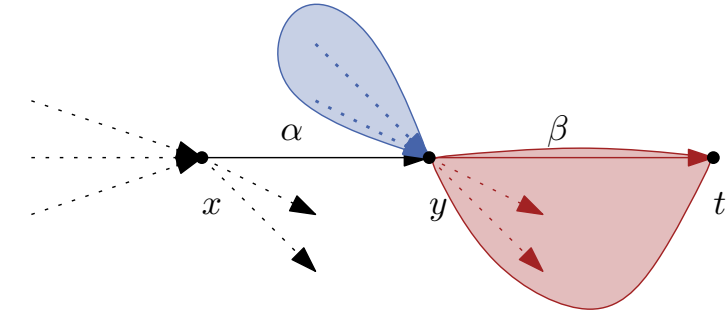
Complexity of Dynamic Flows and Cuts

- Gadgets provide structural insight into dynamic cuts



Complexity of Dynamic Flows and Cuts

- Gadgets provide structural insight into dynamic cuts
- Cut complexity aligns with computational complexity



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